Central bank’s macroeconomic projections and learning

Giuseppe Ferrero† Alessandro Secchi‡
Bank of Italy Bank of Italy
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Abstract

We study the impact of the publication of central bank’s macroeconomic projections on the dynamic properties of an economy where: (i) private agents have incomplete information and form their expectations using recursive learning algorithms, (ii) the short-term nominal interest rate is set as a linear function of the deviations of inflation and real output from their target level and (iii) the central bank, ignoring the exact mechanism used by private agents to form expectations, assumes that it can be reasonably approximated by perfect rationality and releases macroeconomic projections consistent with this assumption.

Results in terms of stability of the equilibrium and speed of convergence of the learning process crucially depend on the set of macroeconomic projections released by the central bank. In particular, while the publication of inflation and output gap projections enlarges the set of interest rate rules associated with stable equilibria under learning and helps agents to learn faster, the announcement of the interest rate path exerts the opposite effect. In the latter case, in order to stabilize expectations and to speed up the learning process the response of the policy instrument to inflation should be stronger than under no announcement.

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†Email: giuseppe.ferrero@bancaditalia.it
‡Email: alessandro.secchi@bancaditalia.it
1 Introduction

The current commonly-held view about monetary policy is that it influences economic decisions mainly through its impact on expectations (Blinder, 2000; Woodford, 2005; Svensson, 2006). One way in which a credible central bank can directly affect private expectations is through the release of information about its own view on the future evolution of macroeconomic variables and, in particular, of its policy intentions. This can be done at different levels of precision, from the release of vague verbal hints to the publication of unambiguous numerical projections.\footnote{For an empirical analysis of the effects of qualitative announcements of monetary policy intentions see Bernanke, Rehinhart, and Sack, 2004; Gurkaynak, Sack, and Swanson, 2005; and Rudebusch, 2006. For the effects of the publication of numerical interest rate paths see, Archer, 2005; Moessner and Nelson, 2008; and Ferrero and Secchi, 2009.} It has been argued that the main advantage associated with the use of more precise communication is that it allows a stricter control of private expectations and, in turn, greater macroeconomic stability (Woodford, 2005; Rudebush and Williams, 2008).\footnote{Other positive effects of the release of precise information regarding the future evolution of the economy are that (i) it also enhances the efficient pricing of financial assets (Archer, 2005; Kahn, 2007; Svensson, 2004), (ii) it increases the central bank’s accountability (Mishkin, 2004) and (iii) it fosters the production of good forecasts by the central bank (Archer, 2005).} However, it has also been pointed out that the release of accurate information about macroeconomic expectations might involve a series of drawbacks. On top of the general claim that the provision of public information is not necessarily beneficial (Morris and Shin, 2002), recent studies have reported the possibility that an explicit announcement of central bank’s expectations, and in particular of its policy intentions, might reduce credibility, especially when the public ignores its conditional nature or misinterprets the precision of the received information (Mishkin, 2004; Khan, 2007; Woodford, 2005; Rudebusch and Williams, 2008). The tension between benefits and costs associated with the disclosure of information about central bank’s macroeconomic expectations remains unresolved.

Our contribution to this debate starts from the observation that an important issue that has received minor attention in the literature is the analysis of the effects of the announcement of macroeconomic projections in an environment where agents are learning. An exception in this respect is the work of Eusepi and Preston (2010). In their model, monetary policy stabilization is conducted in the presence of two informational frictions. First, the central bank has imperfect information about the state of the economy and sets the current interest rate as a function of its forecast of the current inflation and output gap. Second, private agents have an incomplete
understanding of the functioning of the economy and forecast the variables which are relevant to their decision process using past data. In such an environment, where self-fulfilling expectations are possible, it is shown that the provision of detailed information about policy intentions favors the alignment of private and central bank’s expectations – anchoring of expectations – thus restoring macroeconomic stability.

In this work we analyze an economy which shares with Eusepi and Preston (2010) the assumptions that the information available to private agents is incomplete and that they update their expectations using recursive learning algorithms. Moreover, also in our model the central bank implements monetary policy according to Taylor rules. However, we depart from their framework in assuming that the central bank is endowed with complete information about the current state of the economy and that it publishes macroeconomic projections based on the hypothesis that private agents are perfectly rational. We believes this hypothesis represents in a plausible and realistic way what is done by most of the central banks which disclose their expectations about short term interest rates. The public is then assumed to form its macroeconomic expectations as a weighted average of the projections released by the central bank and the prediction obtained through its learning algorithm.

We study the impact of the publication of central bank’s macroeconomic projections on the stability of the equilibrium and on the speed of convergence of the learning process of private agents. It turns out that results crucially depend on the set of macroeconomic projections released by the central bank. In particular we show that the release of interest rate projections restricts the set of policy rules

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3 The Norges Bank produces forecasts using a core macroeconomic DSGE model with "rational agents reacting to exogenous disturbances" (Brubakk et al, 2006), the Swedish Riksbank uses a macroeconomic general equilibrium model derived under the assumptions of "optimizing behaviors and rational expectations" (Adolfson et al., 2007) and the Central Bank of Iceland uses a model where expectations "are assumed to be rational, i.e. consistent with the model structure (model consistent expectations)". The Reserve Bank of New Zealand represents, in part, an exception as at the core of its Forecasting and Policy System has a general equilibrium macro-model where expectations are modeled "as some weighted combination of the model-consistent forecast and some other function of the recent data" (Black et al., 1997). Learning, however, is not taken explicitly into account. For completeness it should also be noticed that central banks are aware of the limits of macroeconomic models and also of the rational expectation hypothesis. In describing the model used at the Reserve Bank of New Zealand, Black et al. (1997) observe that "a valuable next step would be to specify how agents learn about the new policy rules, although as yet there is no generally-accepted theory of learning in macroeconomics". For this reason macroeconomic projections are often "corrected" with judgmental factors before being disclosed to the public. The effect of this judgment component on the learning process of private agents is an interesting issue only partially addressed in this paper – see Section 5 – and it deserves further research.

4 Similarly, we may assume that a fraction of private agents in the economy uses its own learning procedure to form expectations, while the remaining fraction fully internalizes the central bank’s announcement.
consistent with a stable equilibrium and reduces the speed of learning. This result overturns the main conclusion of Eusepi and Preston (2010) which states that more transparency about future policy rates favors macroeconomic stability. On the contrary the publication of projections about inflation and output gap helps agents to learn faster and enlarges the set of monetary policies associated with stable equilibria under learning.

The result that the disclosure of the interest rate projections undermines the macroeconomic stability when the interest rule adopted by the central bank is not sufficiently aggressive against inflation can be explained as follows. In a New-Keynesian framework where private agents are learning, an initial (positive) expectation bias leads to higher inflation both directly through the Phillips curve and indirectly through the real interest rate that affects the output gap in the IS curve. A policy rule that reacts to inflation (and output gap) introduces a feedback element in the IS curve that helps to offset the initial bias – if the response to inflation is sufficiently large. However, by publishing the interest rate projections obtained under the (incorrect) assumption that private agents are rational, the central bank is not taking into account the systematic mistakes that private agents are doing along the learning process and, therefore, reduces its ability to contrast the cumulative movement away from the rational expectation equilibrium (REE) through the interest rate rule – or in other terms it weakens the positive feedback element in the IS curve. As a result initial expectations biases tend to be amplified by the announcement, agents need a longer period of time to learn and the convergence toward the REE is slower. The overall system becomes more vulnerable to self-fulfilling expectations. This implies that in order to obtain stability under learning and to favor a fast convergence of the learning process, a central bank which decides to publish the interest rate path obtained under the assumption that private agents are fully rational should also choose a policy rule characterized by a response to inflation which is stronger than in the case of no announcement.

Publishing output gap and inflation projections has opposite implications. While the information about the policy rate (the instrument variable of the model) is indirectly exploited by private agents in order to form expectations about future inflation and output gap (the control variables of the model), information about these two variables is used directly to predict their future behaviors. Initial expectation biases are immediately reduced with no need for the stabilizing properties of interest rate rules that by responding to actual (or expected) inflation and output gap introduce the positive feedback in the IS curve. Therefore, by announcing its inflation and
output gap expectations, the central bank helps agents to learn faster and enlarges the set of monetary policies associated with stable equilibria under learning.

The publication of interest rate projections is an aspect of monetary policy communication which has recently generated an extensive debate, both among policymakers and academics. Our analysis provides new results in favor of a prudential approach in disclosing information about expected interest rates. In fact they imply that when the interest rate rule is not sufficiently aggressive against inflation the implementation of this communication strategy generates instability. It also emerges that the larger the weight given by private agents on central bank’s interest rate projections, the more aggressive has to be the interest rate rule to preserve the system from instability. In particular it turns out that when such a weight is above a certain threshold the set of policy rules which generate instability becomes even larger than the one associated with the no disclosure benchmark.

From a more general point of view it is however useful to observe that our results are not necessarily against the publication of interest rate projections. In fact, even when private agents are learning, it cannot be excluded the possibility that the central bank, by taking into account the true mechanism used by private agents to form expectations, might devise interest rate projections which strengthen the stability of the economy and increase the speed of convergence of private expectations towards rationality.

The paper is organized as follows. In Section 2 we develop the baseline model; in Section 3 we analyze the effect of publishing the projections about the policy instrument in terms of stability under learning and speed of convergence; in Section 4 we analyze the alternative scenario where the central bank also publishes its expectations about the output gap and inflation; in Section 5 we consider some extensions. Section 6 concludes.

2 The model

We assume that under rational expectations the economy evolves according to the following standard New-Keynesian model:

\[ x_t = E_t x_{t+1} - \varphi (i_t - E_t \pi_{t+1}) + g_t \]  \hspace{1cm} (2.1)

\[ \pi_t = \alpha x_t + \beta E_t \pi_{t+1} + u_t, \]  \hspace{1cm} (2.2)
where \( x_t \) denotes the output gap, \( \pi_t \) is inflation and \( i_t \) the short-term nominal interest rate at time \( t \). The operator \( E_t \) denotes rational expectations conditional to the information set available at \( t \). Finally, \( g_t \) and \( u_t \) are, respectively, a demand and a cost-push shock. These two shocks evolve according to:

\[
\begin{align*}
g_t &= \rho_g g_{t-1} + \varepsilon_{gt} \quad \text{and} \quad u_t = \rho_u u_{t-1} + \varepsilon_{ut}, \\
\end{align*}
\]  

where \( \varepsilon_{gt} \) and \( \varepsilon_{ut} \) are mutually orthogonal white noises with variances \( \sigma^2_g, \sigma^2_u \).

We supplement equations (2.1)-(2.3) with a standard contemporaneous Taylor rule.\(^5\)

\[
i_t = \gamma + \gamma_x x_t + \gamma_\pi \pi_t.
\]  

The stochastic dynamic system (2.1)-(2.4) can be rewritten more compactly as:

\[
y_t = Q + F \times E_t y_{t+1} + Sw_t, \tag{2.5}
\]  

with

\[
w_t = \Psi w_{t-1} + \varepsilon_t
\]  

where

\[
y_t = \begin{bmatrix} \pi_t & x_t & i_t \end{bmatrix}', \quad w_t = \begin{bmatrix} u_t & g_t \end{bmatrix}', \quad \varepsilon_t = \begin{bmatrix} \varepsilon_{u,t} & \varepsilon_{g,t} \end{bmatrix}'.
\]  

and the link between the parameters in equations (2.1)-(2.4) and matrices \( Q, F \) and \( S \) is derived in Appendix 1.

It is well known that under rational expectations, the linear system (2.5) has a unique non-explosive solution if and only if all eigenvalues of the \( F \) matrix are inside the unit circle.\(^6\) As shown in Bullard and Mitra (2002) this condition reduces to have

\[
\gamma_\pi > 1 - \frac{(1 - \beta)}{\alpha} \gamma_x. \tag{2.6}
\]

When this condition is satisfied the unique non-explosive solution is of the minimum state variable (MSV) form

\[
y_t = A + Bw_t \tag{2.7}
\]

\(^5\)In Section 5 we show that the results of our analysis do not change when the central bank is assumed to implement monetary policy through a Taylor rule based on forward looking variables.

\(^6\)See for example McCallum, 2004.
where $A$ is a $(3 \times 1)$ vector and $B$ a $(3 \times 2)$ matrix.

We now consider a departure from the hypothesis of rational expectations. In particular we assume that private agents know the sequence of shocks that hits the economy (up to the current time $t$) and the actual values of output gap, inflation and interest rates (up to time $t - 1$). We also assume that private agents are aware of the functional form of the MSV solution (2.7), but ignore the value of the $A$ and $B$ matrices.

Under these hypotheses, the economy evolves according to

$$ y_t = Q + F \times E^*_t y_{t+1} + Sw_t, \quad (2.8) $$

$$ w_t = \Psi w_{t-1} + \varepsilon_t $$

where the operator $E^*_t$ denotes expectations conditional to the information set available at $t$ and the "*" symbol is used to stress that expectations are not fully rational. In particular, we assume that, in each period $t$, private agents obtain estimates $\hat{A}_t$ and $\hat{B}_t$ of the corresponding matrices of equation (2.7) using a recursive learning algorithms as in Marcet and Sargent (1989) and Evans and Honkapohja (2001). These estimates are in turn used to form their own forecasts about the evolution of the endogenous variables at $t + 1$, $E^*_t y_{t+1}$. This procedure is an example of adaptive real-time learning, which basic idea is that agents follow a standard statistical or econometric procedure for estimating the perceived law of motion (PLM) of the endogenous variables.

Stacking estimates $\hat{A}_t$ and $\hat{B}_t$ in a matrix $\hat{\Gamma}_t$, and the constant term and the shocks $u_t$ and $g_t$ in vector $z_t$,

$$ \hat{\Gamma}_t = \left[ \begin{array}{c} \hat{A}_t' \\ \hat{B}_t' \end{array} \right]' \quad \text{and} \quad z_t = \left[ \begin{array}{c} 1 \\ u_t' \\ g_t' \end{array} \right]' $$

the matrix $\hat{\Gamma}_t$ is estimated recursively from past data according to

$$ \hat{\Gamma}_t = \hat{\Gamma}_{t-1} + t^{-1} \hat{R}_{t-1} z_{t-1} \left( y_{t-1} - z_{t-1}' \hat{\Gamma}_{t-1} \right) \quad (2.9) $$

where

$$ \hat{R}_t = \hat{R}_{t-1} + t^{-1} \left( z_{t-1} z_{t-1}' - \hat{R}_{t-1} \right). \quad (2.10) $$

According to expressions (2.9)-(2.10), in each period private agents update their
estimates of $A$ and $B$ by a term that depends on the last prediction errors.\footnote{Note in particular that $\hat{\Gamma}_t$ depends on information available up to $t - 1$.} At the beginning of each period, when the public knows the realization of the shocks but endogenous variables are still to be determined, the law of motion perceived by private agents is

$$y_t^{PLM} = z_t \hat{\Gamma}_t,$$  \hspace{1cm} (2.11)

which implies that private agents compute their forecasts of endogenous variables according to\footnote{We assume that $\Psi$ is known. This assumption is commonly adopted in the learning literature and does not affect the results (see for example Evans and Honkapohja, 2001).}

$$E_t^* y_{t+1} = \hat{A}_t + \hat{B}_t \Psi w_t.$$  \hspace{1cm} (2.12)

In order to study whether the recursive least-squares estimates $\hat{A}_t$ and $\hat{B}_t$ converge to the corresponding matrices which define the MSV solution under RE we refer to the concept of expectation stability (E-stability) described in Evans and Honkapohja (2001).

The E-stability principle focuses on the mapping from the estimated parameters – the perceived law of motion (2.11) – to the true data generating process – the actual law of motion, ALM – obtained by inserting expectations (2.12) into the system (2.8),

$$y_t = Q + F \hat{A}_t + \left( F \hat{B}_t \Psi + S \right) w_t.$$  \hspace{1cm} (2.13)

The resulting mapping from the PLM to the ALM is thus given by

$$T(\hat{A}_t, \hat{B}_t) = (Q + F \hat{A}_t, F \hat{B}_t \Psi + S).$$  \hspace{1cm} (2.14)

Under some regularity conditions (here satisfied)\footnote{See Chapter 6 of Evans and Honkapohja (2001).}, the E-stability principle states that the MSV solution (2.7) is stable under least squares learning if it is locally asymptotically stable under the ordinary differential equations (ODE)

$$\frac{\partial}{\partial \tau}(A) = T_A(A) - A$$  \hspace{1cm} (2.15)

$$\frac{\partial}{\partial \tau}(B) = T_B(B) - B,$$  \hspace{1cm} (2.16)

where $\tau$ denotes “notional” or “artificial” time and $T_A(A) = Q + FA$ and $T_B(B) =$
E-stability conditions are readily obtained by computing the derivative of the ODE’s
\[
\frac{d(T_A(A) - A)}{dA} \quad \text{and} \quad \frac{d(T_B(B) - B)}{dB}
\]
and checking whether all their eigenvalues have negative real part. If this condition is satisfied, the economy described by equations (2.8)-(2.10), where agents form expectations using recursive learning algorithms, converges in the long run to the one described by equations (2.5) and (2.7), were agents are fully rational.

As shown in Bullard and Mitra (2002) expression (2.6) provides also necessary and sufficient condition for E-stability.

3 Central Bank interest rate path communication

The aim of this section is to analyze the effects of publishing the interest rate path in terms of E-stability and speed at which agents learn\textsuperscript{10}. While agents’ expectations evolve according to the learning procedure described in the previous section, we retain the assumption that the central bank produces its own forecasts assuming that private agents are perfectly rational. As we said in the introduction this assumption mostly reflects the fact that in practice the central banks that announce their policy path obtain their projections - to a large extent - from macroeconomic models solved under the rational expectation hypothesis.

In order to study the effects of the announcement we write the IS and the Phillips curve \( T - 1 \) periods ahead and substitute them in expressions (2.1) and (2.2)\textsuperscript{11}

\[
x_t = E_t^* x_{t+T} - E_t^* \sum_{j=0}^{T-1} (\varphi i_{t+j} - \varphi \beta \pi_{t+j} - g_{t+j}) \quad (3.1)
\]

and

\[
\pi_t = \beta^T E_t^* \pi_{t+T} + E_t^* \sum_{j=0}^{T-1} \beta^j (\alpha x_{t+j} + u_{t+j}) \quad (3.2)
\]

It is worth to notice that in order to obtain equations (3.1) and (3.2) we are using the law of iterated expectations hypothesis, that holds under both RE and

\textsuperscript{10}In terms of determinacy, nothing changes since the model under rational expectations does not change when the central bank announces its interest rate projections.

\textsuperscript{11}Here, as in Rudebusch and Williams (2006), we substitute separately the \( T \)-period ahead IS and the Phillips curves into the time-\( t \) IS and the Phillips curve. Results do not change if we consider a more general forward representation of this system of equations.
least square learning (Evans, Honkapohja and Mitra, 2003). This formulation points out the central role not only of actual real interest rate, but also of expected future short term real interest rates in determining today output and inflation.

### 3.1 E-Stability of the REE

For simplicity we assume that the central bank announces only the next period expected interest rate.\(^{12}\) In this case we can write (3.1) and (3.2) for \(T = 2\), as

\[
\pi_t = \beta^2 E_t^* \pi_{t+2} + \alpha x_t + u_t + \beta \alpha E_t^* x_{t+1} + \beta E_t^* u_{t+1} \tag{3.3}
\]

\[
x_t = E_t^* x_{t+2} - \varphi (i_t - E_t^* \pi_{t+1} + E_t^* i_{t+1} - E_t^* \pi_{t+2}) + g_t + E_t^* g_{t+1}. \tag{3.4}
\]

Ferrero and Secchi (2009) study the case of the Reserve Bank of New Zealand, that publishes its own interest rate projections since 1999, and show that market expectations on short term interest rates respond in a significant and consistent way to the unexpected component of the published path, even though adjustment is not complete. In order to take into account the possibility that the public moves its expectations only partially in the direction of the announcement, we assume that private agents expectations about the expected interest rate depend on both central bank’s announcement and their own estimates.\(^{13}\) Let \(0 \leq (1 - \lambda_1) \leq 1\) be the weight that agents assign to the central bank’s announcement,

\[
E_t^* i_{t+1} = (1 - \lambda_1) E_t^{CB} i_{t+1} + \lambda_1 E_t^{RLS} i_{t+1} \tag{3.5}
\]

where

\[
E_t^{CB} i_{t+1} = a_i + \rho_u b_{u,i} u_t + \rho_g b_{g,i} g_t \tag{3.6}
\]

and \(a_i\), \(b_{u,i}\) and \(b_{g,i}\) are the coefficients that appear in the rational expectation equilibrium (2.7), while

\[
E_t^{RLS} i_{t+1} = a_{i,t} + \rho_u b_{u,i,t} u_t + \rho_g b_{g,i,t} g_t \tag{3.7}
\]

where \(a_{i,t}\), \(b_{u,i,t}\) and \(b_{g,i,t}\) are estimated recursively.

\(^{12}\) In Section 5 we consider also announcements over longer horizons.

\(^{13}\) Alternatively, we may assume that a fraction of private agents in the economy uses its own learning procedure to form expectations, while the remaining fraction, fully internalizes the central bank’s announcement. The possibility of having a weight on the released information different than one is particularly relevant when we analyze the case in which the central bank announces both the policy path and the inflation and output gap projections (see Section 4).
We also assume that the central bank does not release information about its expected inflation and output gap\textsuperscript{14}

\[ E_t^* \pi_{t+i} = E_t^{RLS} \pi_{t+i} \text{ and } E_t^* x_{t+i} = E_t^{RLS} x_{t+i}. \]

Under these assumptions equations (3.3) and (3.4) can be written as

\[ y_t = \tilde{Q} + \tilde{F} \times E_t^* y_{t+1} + \tilde{V} \times E_t^* y_{t+2} + \tilde{S} w_t, \]  

(3.8)

where \( \tilde{Q}, \tilde{F}, \tilde{V} \) and \( \tilde{S} \) are derived in Appendix 2.

Private agents' forecasts under recursive learning are computed from the estimated PLM

\[ y_t = A + B w_t \]

from which we compute the expectations

\[ E_t y_{t+1} = A + B \Psi w_t \text{ and } E_t y_{t+2} = A + B \Psi' \Psi w_t. \]

The actual law of motion of \( y_t \) is

\[ y_t = \left( \tilde{Q} + \tilde{F} A + \tilde{V} A \right) + \left( \tilde{F} B \Psi + \tilde{V} B \Psi' \Psi + \tilde{S} \right) w_t, \]  

(3.9)

the resulting mapping from the PLM to the ALM is

\[ T(A, B) = (\tilde{Q} + \left( \tilde{F} + \tilde{V} \right) A, \tilde{F} B \Psi + \tilde{V} B \Psi' \Psi + \tilde{S}) \]  

(3.10)

and the associated ordinary differential equations used to study E-stability are

\[ \frac{\partial}{\partial \tau} (A) = \tilde{Q} + \left( \tilde{F} + \tilde{V} \right) A - A, \]  

(3.11)

\[ \frac{\partial}{\partial \tau} (B) = \tilde{F} B \Psi + \tilde{V} B \Psi' \Psi + \tilde{S} - B. \]  

(3.12)

In the following proposition we state the conditions under which the REE is E-stable and compare them with those obtained under no announcement.

\textbf{Proposition 1.} Let \( \varphi \gamma_x + \alpha \varphi \gamma_n + 1 \neq 0 \). In an economy that (i) evolves according to the system of equations (3.8), where (ii) at time \( t \) the central bank publishes the time

\textsuperscript{14}The case in which the central bank releases also inflation and output gap projections is analyzed in Section 4.
t+1 interest rate projection consistent with the REE and (iii) private agents assign weight $0 \leq (1 - \lambda_1) \leq 1$ to these projections, revealing the interest rate path makes condition for stability under learning more stringent than under no announcement. In particular, the necessary and sufficient condition for E-stability of the equilibrium (2.7) is

$$\gamma_x > \frac{2}{(1 + \lambda_1)} - \frac{1 - \beta}{\alpha} \gamma_x. \tag{3.13}$$

Proof. See Appendix 2. \hfill \Box

The Phillips curves (2.2) and (3.2) being equilibrium conditions imply that each percentage point of permanently higher inflation determines a permanently higher output gap of $(1 - \beta)/\alpha$ percentage points. Therefore, when the policy maker does not announce future policy intentions, expression (2.6) states that necessary and sufficient condition for E-stability is that the long-run increase in the nominal interest rate prescribed by policy rules with contemporaneous endogenous variables should be larger than the permanent increase in the inflation rate. Applying a similar reasoning to the case where the central bank announces the next period expected interest rate, expression (3.13) states that necessary and sufficient condition for E-stability is that the long-run increase in the nominal interest rate should be at least $2/(1 + \lambda_1)$ times as big as the permanent increase in the inflation rate. For $0 \leq (1 - \lambda_1) < 1$, this implies a larger response than under no announcement.

In a world where private agents are learning from past data – and along their learning process they produce biased predictions of the main macro variables – the result that E-stability conditions are more stringent under the announcement of the expected interest rate crucially depends on the assumption that the central bank’s projections are obtained assuming that private agents are perfectly rational – that is a projection that in the long run, when the agents in the economy have enough data to estimate correctly the parameters of the model, will be (possibly) correct, but along the learning process will be inaccurate. As a result, initial expectations biases tend to be amplified by the announcement, the overall system becomes more vulnerable to self-fulfilling expectations and in order to stabilize expectations the long-run increase in the nominal interest rate should be at least $2/(1 + \lambda_1)$ times as big as the permanent increase in the inflation rate.\textsuperscript{15}

\textsuperscript{15}Based on this argument we can correctly conclude that a central bank that takes into account the private agents learning process, by announcing the interest rate path consistent with the MSV solution would help to stabilize expectations. In fact, realizing that agents are learning means that previous beliefs, $\Gamma_{t-1}$, are an additional state variable of the system and the MSV solution would be a function also of it. An interest rate that responds directly to this variable would have
Let’s consider an example where private agents have an initial positive bias in expected inflation. This positive bias will lead to higher inflation both directly through the Phillips curve and indirectly through the real interest rate that affects the output gap in the IS curve and therefore inflation (in the Phillips curve). A policy rule that reacts directly to inflation (and output gap) introduces a feedback element in the IS curve that helps to offset the initial bias – if the response to inflation is sufficiently large, as stated in condition (2.6). By publishing the interest rate projections obtained under the (incorrect) assumption that private agents are rational, the central bank is not taking into account the systematic mistakes that private agents are doing along the learning process and, therefore, reduces its ability to contrast the cumulative movement away from REE through the interest rate rule – or in other terms it weakens the positive feedback element in the IS curve.

Figure 1: E-stability under no announcement, \((1 - \lambda_1) = 0\), and under a fully internalized announcement of the interest rate path, \((1 - \lambda_1) = 1\).

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the same stabilizing properties of a policy rule that respond to current (or expected) inflation and output gap, as it would be able to offset the initial deviations from the REE.
Figure 1 compares the regions of E-stability in the $(\gamma_x, \gamma_\pi)$ space under no announcement and under announcement of the interest rate path. The lower region shows the set of policies that implies instability under learning when the central bank is silent about the interest rate path, $(1 - \lambda_1) = 0$. Publishing the path, the central bank enlarges the region of instability – the larger the weight the agents give to the announcement, the larger the region of instability under learning. In particular, when the weight that private agents give to the projection is larger than 0.65, the classical Taylor rule with $\gamma_x = 0.5$ and $\gamma_\pi = 1.5$ would fall in the region of instability under learning.

### 3.2 Speed of convergence

In the previous sections we have analyzed the effect of announcing the interest rate path on the long-run properties of the equilibrium under learning. Combinations of $(\gamma_x, \gamma_\pi)$ that imply a determinate and E-stable REE are usually defined in the literature as "good" policies (Bullard and Mitra, 2002). The concept of speed of convergence can be used in order to refine further the set of these policies (see Ferrero, 2007). If convergence is rapid, we may think to focus on asymptotic behaviors, because the economy would typically be close to the REE. In this case the publication of projections obtained under the assumption of fully rational private agents would have a minor effect on the stability of the economy. Conversely, if convergence is slow, the economy would be far from the REE for a long period of time and its behavior would be dominated by the transitional dynamics. In this case the consequences associated to the incorrect assumption that private agents are perfectly rational may result significantly more severe.

In the literature, the speed of convergence of recursive least square learning algorithms in stochastic models has been analyzed mainly through numerical procedures and simulations. The few analytical results on the transition to the rational expectations equilibrium environment are obtained by using a theorem of Benveniste, Metiver and Priouret (1990) that relates the speed of convergence of the learning process to the derivative of the associated ODE at the fixed point. In the present case, the ODE’s to be analyzed are those described in expressions (3.11)–(3.12).

We define

$$S_1 = \left\{ \gamma_\pi, \gamma_x : \gamma_\pi > \max \left[ \frac{(\beta^2 + 2\alpha \phi)}{\alpha \phi (1 + \lambda_1 + \beta)} \frac{(1 + \lambda_1 - \beta^2)}{\alpha (1 + \lambda_1 + \beta)} \gamma_x \right] \right\}$$
the set of policies – combinations of $\gamma_\pi$ and $\gamma_x$ – under which all the eigenvalues of the $\tilde{F} + \tilde{V}$ matrix have real part smaller than 0.5.

The following proposition, adapting arguments from Marcet and Sargent (1995), shows that by choosing the $\gamma_\pi$ and $\gamma_x$, the policy-maker not only determines the level of inflation and output gap and their stability in the long run, but also the speed at which the economy converges to the REE, i.e. the speed at which agents learn.

**Proposition 2.** In an economy that (i) evolves according to the system of equations (3.8), where (ii) private agents assign weight $0 \leq (1 - \lambda_1) \leq 1$ to the central bank’s announcement, and (iii) the central bank chooses a policy $(\gamma_\pi, \gamma_x) \in S_1$, then

$$\sqrt{t}(\Gamma_t - \Gamma) \xrightarrow{D} N(0, \Omega_{\Gamma})$$

where the matrix $\Omega_{\Gamma}$ satisfies

$$\left[\frac{1}{2} (F + V - I)\right] \Omega_{\Gamma} + \Omega_{\Gamma} \left[\frac{1}{2} (F + V - I)\right]' + E [T(T') - \Gamma')] [T(T') - \Gamma')] = 0$$

(3.14)

**Proof.** see Appendix 3.

If the conditions of Proposition 2 are satisfied, the estimated $\Gamma_t$ converges to the REE, $\Gamma$, at root-$t$ speed. Root-$t$ is the speed at which, in classical econometrics, the least square estimator converges to the true value of the parameters estimated. Note that the formula for the variance of the estimator $\Gamma_t$ is modified with respect to the classical case. In particular, if $(\gamma_\pi, \gamma_x) \in S_1$, the higher the eigenvalues of $\tilde{F} + \tilde{V}$, the larger the asymptotic variance of the limiting distribution (Marcet and Sargent, 1995). In this case, convergence is slower in the sense that the probability that a shock will drive the estimates far away from the REE is higher and the period of time that agents need in order to learn it back is larger (see Ferrero, 2007).

**Proposition 3.** In an economy that (i) evolves according to the system of equations (3.8), where (ii) private agents assign weight $0 \leq (1 - \lambda_1) \leq 1$ to the central bank’s announcement, and (iii) the central bank chooses a policy $(\gamma_\pi, \gamma_x) \in S_1$, revealing the path makes condition for root-$t$ convergence more stringent than under no announcement. In particular, the smaller the weight to the announcement, the larger the set of policies under which private agents learn at root-$t$ speed.

**Proof.** see Appendix 4.
In Figure 2 we focus on the two extreme cases where there is no announcement, \((1 - \lambda_1) = 0\), and where private agents fully internalize the announcement, \((1 - \lambda_1) = 1\). Figure 2 shows that (i) the set of combinations \((\gamma_x, \gamma_\pi)\) resulting in root-\(t\) convergence is much smaller than the one under which E-stability holds and (ii) the region of "fast" convergence (i.e. root-\(t\) convergence) is smaller when the central banks announces its policy (the smallest region in the upper-left corner) than under no announcement (the sum of the two upper-left corner regions).

Figure 2: E-stability & root-\(t\) convergence under no announcement and under fully internalized announcement of expected interest rates

Let’s now define

\[
S_2 = \left\{ (\gamma_\pi, \gamma_x) \in R^2_+ : \frac{2}{(1 + \lambda_1)} - \frac{(1 - \beta)}{\alpha} \gamma_x < \gamma_\pi < \max \left[ \frac{\frac{\beta^2 + 2\alpha \varphi}{\alpha \varphi(1 + \lambda_1 + \beta)} - \frac{1 + \lambda_1 - \beta^2}{\alpha(1 + \lambda_1 + \beta)} \gamma_x}{\frac{4(2\beta + 1)\alpha \varphi - (2\beta^2 - 1)}{(2\beta + 1)(1 + 2\lambda_1)\alpha \varphi} - \frac{1 - 2\beta^2}{(1 + 2\beta)\alpha} \gamma_x} \right] \right\}
\]
the set of policies under which all the eigenvalues of $\tilde{F} + \tilde{V}$ have real part less than one but not all have real part less than 0.5.

Although Propositions 2 and 3 do not apply when $(\gamma_{\pi}, \gamma_{x}) \in S_2$, it can be shown by Monte Carlo calculations that under those policies the effects of initial conditions fail to die out at an exponential rate (as it is needed for root-t convergence) and agents’ beliefs converge to rational expectations at a rate slower than root-$t$. In particular, also when $(\gamma_{\pi}, \gamma_{x}) \in S_2$, the link between the derivative of the ODE and the speed of convergence holds.

Marcet and Sargent (1995) suggest a numerical procedure to obtain an estimate of the rate of convergence when $(\gamma_{\pi}, \gamma_{x}) \in S_2$. In this case it is possible to define the rate of convergence, $\delta$, for which

$$t^\delta (\Gamma_t - \Gamma) \overset{D}{\to} F$$

for some non-degenerate well-defined distribution $F$ with mean zero and variance $\Omega_F$.

Expression (3.15) can be used to obtain an approximation of the rate of convergence$^{16}$ for large $t$. Since $E \left[ t^\delta (\Gamma_t - \Gamma) (\Gamma_t - \Gamma)' \right] \to \Omega_F$ as $t \to \infty$, we have that

$$\frac{E \left[ t^{2\delta} (\Gamma_t - \Gamma) (\Gamma_t - \Gamma)' \right]}{E \left[ (tz)^{2\delta} (\Gamma_{tz} - \Gamma) (\Gamma_{tz} - \Gamma)' \right]} \to 1 \quad \text{or} \quad \delta = \frac{1}{2 \log z} \log \frac{E \left[ (\Gamma_t - \Gamma) (\Gamma_t - \Gamma)' \right]}{E \left[ (\Gamma_{tz} - \Gamma) (\Gamma_{tz} - \Gamma)' \right]}.$$

The expectations can be approximated by simulating a large number of independent realizations of length $t$ and $tz$, and calculating the mean square distance from $\Gamma$ across realizations for each coefficient. Table 1 reports the rate of convergence, $\delta$, the real part of the largest eigenvalue of the $\left( \tilde{F} + \tilde{V} \right)$ matrix, $k$, the number of quarters needed in order to halve the initial expectation error, $T_{1/2}$, and the number of quarters needed in order to reduce to one third the initial error, $T_{1/3}$, for different values of $(\gamma_{\pi}, \gamma_{x}) \in S_2$.$^{17}$

Calculations show that (i) for a given response to inflation, $\gamma_{\pi}$, the larger the response to output gap, $\gamma_{x}$, the higher the real part of the larger eigenvalue, the smaller $\delta$ and the lower the speed of convergence; (ii) the opposite relation holds for

$^{16}$The calculation of the rate of convergence is based on the assumption that such a $\delta$ exists.

$^{17}$Simulations are obtained under Clarida, Galí and Gertler (CGG, 2000) calibration: US data, $\varphi = 4$, $\alpha = 0.075$, $\beta = 0.99$; We use quarterly interest rates and we measure inflation as quarterly changes in the log of prices. Therefore our CGG calibration divides by 4 the $\alpha$ and multiplies by 4 the $\varphi$ reported by CGG (see also Honkapohja and Mitra, 2004).
Table 1: Speed of convergence and simulations

<table>
<thead>
<tr>
<th></th>
<th>$\gamma_\pi = 1.5$</th>
<th>$\gamma_\pi = 2.5$</th>
<th>$\gamma_\pi = 3.5$</th>
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<td>$\lambda = 0$</td>
<td>$\lambda = 1$</td>
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<tr>
<td>$T_{1/2}$</td>
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<td>N.A.</td>
<td>23</td>
</tr>
<tr>
<td>$T_{1/3}$</td>
<td>&gt;400</td>
<td>N.A.</td>
<td>&gt;400</td>
</tr>
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</tr>
<tr>
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<td>67</td>
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<td>$\gamma_x = 1$</td>
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<td></td>
<td>$\delta$</td>
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<td>78</td>
</tr>
<tr>
<td>$T_{1/3}$</td>
<td>&gt;400</td>
<td>N.A.</td>
<td>&gt;400</td>
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</tbody>
</table>

NOTE: Initial expectation error is 10 per cent of the REE. In all simulations we compute the rate of convergence, $\delta$, with 1000 independent realizations for $t=9000$ and $t_z=10000$ periods; $k$ is the real part of the largest eigenvalue of the $F + V$ matrix; $T_{1/2}$ indicates the quarters needed in order to reduce the inflation forecast error to one half of the initial bias; $T_{1/3}$ indicates the quarters needed in order to reduce the inflation forecast error to one third of the initial bias.

In order to formally map elements of the set of policy rules into a measure of the speed of convergence we define the speed of convergence isoquants.$^{18}$

**Definition 1.** A speed of convergence isoquant-$k$ is a curve in $R^2$ along which all points – combinations $(\gamma_\pi, \gamma_x)$ – imply that the largest eigenvalue of $\tilde{F} + \tilde{V}$ has real

$^{18}$In the definition we tie up speed of convergence with the eigenvalues of the matrix $\tilde{F} + \tilde{V}$. In general, the speed of convergence depends on the eigenvalues of the derivatives of the mapping from PLM to ALM, $T(A)$. In this case, the derivative is equal to $\tilde{F} + \tilde{V}$ (see Ferrero, 2003).
part equal to \( k \). In an economy that evolves according to the system of equations (3.8), the \( k \)-isoquant satisfies

\[
\gamma_\pi = \max \left( \frac{1-2k+\beta^2+2\alpha\phi}{(2k+\beta+\lambda_1)\alpha\phi} \gamma_x, \frac{-\beta^2+2k+\lambda_1}{(2k+\beta+\lambda_1)\alpha\phi} \gamma_x, \frac{\beta^2-k}{\alpha\phi(1-k)} \gamma_x, \frac{k-\beta^2}{\alpha(1-k)} \gamma_x \right). \tag{3.16}
\]

Figure 3: The speed of learning isoquants for \( \lambda_1 = 0 \) (dotted line) and \( \lambda_1 = 1 \) (continue line)

Figure 3 shows the map of the speed of convergence isoquants in the two extreme cases where there is no announcement, \( (1 - \lambda_1) = 0 \), and where the agents fully internalize the announcement, \( (1 - \lambda_1) = 1 \). We observe that, for a given \( \lambda_1 \), the lower the isoquant, the slower the convergence. In fact, from Marcet and Sargent (1995), the larger the real part of the largest eigenvalue of \( \widetilde{F} + \widetilde{V} \), the slower the convergence and the lower the isoquant. Moreover, for a given policy, the speed at
which agents learn is lower if the central banks announces its policy path.

For example, consider the point \((\gamma_\pi, \gamma_x) = (1.5, 0.5)\) in the isoquant map. Being this point below the \(k = 1\) isoquant in the mapping obtained under announcement (dotted lines), private agents never learn. Under no announcement they learn, but very slowly, as the \((\gamma_\pi, \gamma_x) = (1.5, 0.5)\) point is close to the 0.8 isoquant in the continuous-line mapping. Increasing \(\gamma_\pi\) to 2.5 we reach the E-stable region under announcement, but learning is very slow (the point \((\gamma_\pi, \gamma_x) = (2.5, 0.5)\) is between the 0.8 and the 0.9 isoquant in the dotted mapping); under no announcement convergence is much faster, close to root-t (the 0.5 isoquant in the continuous-line mapping).

The next proposition formalizes these results.

**Proposition 4.** In an economy that (i) evolves according to the system of equations (3.8), where (ii) private agents assign weight \(0 \leq (1 - \lambda_1) \leq 1\) to the central bank’s announcement, and (iii) the central bank chooses a policy \((\gamma_\pi, \gamma_x) \in S_2\), for a given \(\gamma_x\), the smaller the weight to the policy path projections, the smaller has to be \(\gamma_\pi\) in order to reach the same speed of convergence. Or in other terms, for a given combination of \((\gamma_x, \gamma_\pi)\), the smaller the weight that private agents assign to the policy path projections, the faster the learning process.

**Proof.** see Appendix 5.

\[\square\]

## 4 Announcing expected inflation and output gap

In the previous sections we have shown that in a world where private agents are learning from past data – along their learning process they produce biased predictions of the main macro variables – a central bank that publishes its projection obtained under the incorrect assumption that private agents are perfectly rational reduces the speed at which agents learn\(^{19}\).

In this section we analyze the implications in terms of E-stability and speed of convergence when the central bank announces its projections about inflation and output gap, possibly in addition to the interest rate path. We assume that also these projections are obtained under the incorrect assumption that private agents are perfectly rational,

\[E_{t}^{CB} y_{t+1} = A + B \Psi w_t.\]

\(^{19}\)Here we are not analyzing the important implications in terms of welfare. In particular we are not saying that a slower convergence will necessarily imply a lower social welfare. For an analysis of speed of convergence and welfare in a New-Keynesian model see Ferrero 2007.
The main difference between the announcement of the policy path and the announcement of inflation and output gap paths is that, while the interest rate (the instrument variable of the model) is implicitly used by private agents in order to form expectations about future inflation and output gap (the control variables of the model), information about output gap and inflation are used directly to predict those variables. Initial expectation biases are immediately reduced with no need for the stabilizing properties of interest rate rules that respond to actual (or expected) inflation and output gap. Therefore, by announcing its inflation and output gap expectations, the central bank helps agents to learn faster and enlarges the set of monetary policies associated with stable equilibria under learning.

Let \(0 \leq (1 - \lambda_2) \leq 1\) be the weight that private agents give to the central bank's announcement of inflation and output gap

\[
E_t^P \pi_{t+1} = (1 - \lambda_2) E_t^{CB} \pi_{t+1} + \lambda_2 E_t^* \pi_{t+1} \\
E_t^P x_{t+1} = (1 - \lambda_2) E_t^{CB} \pi_{t+1} + \lambda_2 E_t^* x_{t+1}.
\]

Under learning the economy evolves according to the system of equation

\[
y_t = \tilde{Q} + \tilde{F} \times E_t^* y_{t+1} + \tilde{V} \times E_t^* y_{t+2} + \tilde{S} w_t. \tag{4.1}
\]

where matrices \(\tilde{Q}, \tilde{F}, \tilde{V}\) and \(\tilde{S}\) are derived in Appendix 7.

### 4.1 Announcing only expected inflation and output gap

First we focus on the case in which the central bank only announces the inflation and output gap projections and private agents partly internalize this announcement to form their expectations, i.e. \(\lambda_1 = 1\) and \(0 < (1 - \lambda_2) \leq 1\).

**Proposition 5.** In an economy that (i) evolves according to the system of equation (4.1), where (ii) the central bank publishes only the projection about inflation and output gap consistent with the REE and (iii) private agents assign weight \(0 < (1 - \lambda_2) \leq 1\) to those projections, revealing the path makes condition for stability under learning less stringent and the region of root-t convergence larger than under no announcement. In particular, the necessary and sufficient condition for

\[20\text{Again, we may assume that a fraction of private agents in the economy uses its own learning procedure to form expectations, while the remaining fraction fully internalizes the central bank’s announcement.} \]
E-stability of the REE is
\[ \gamma_{\pi} > \frac{2\lambda_2 (\beta \lambda_2 + 1) \alpha \varphi - (\beta^2 \lambda_2 - 1) (\lambda_2 - 1)}{(\beta \lambda_2 + 1) (1 + \lambda_2) \alpha \varphi} - \frac{(1 - \beta^2 \lambda_2)}{(\beta \lambda_2 + 1) \alpha} \gamma_x \] (4.2)

Proof. See Appendix 7.

Announcing inflation and output gap projections has opposite implications with respect to publish the interest rate path. The former enlarges the region of policies that imply an E-stable equilibrium and root-t convergence, while the latter enlarges the region of instability and slow convergence.

Figure 4 shows the region of E-stability and root-t convergence when the central bank announces only the inflation and output gap and the private sector gives weight 0.25 to this announcement. It is sufficient that private agents give a little weight to inflation and output gap projections in order to shrink substantially the region of instability under learning and to increase the speed of convergence.

4.2 Announcing expected interest rate, inflation and output gap

In practice, all central banks that publish their own interest rate projections were previously publishing their inflation and output gap expectations. Therefore, we also focus on the case where the central bank announces both the interest rate path and the inflation and output gap projections and the private agents at least partially internalize these announcements to form their expectations.\(^{21}\)

Clearly the two types of announcement have opposite effects in the dynamics of the economy.

In Table 2 we report for different combinations of \(\lambda_1\) and \(\lambda_2\), the speed of convergence and the number of periods needed in order to reduce to 1/3 the initial forecast error, when the central bank sets the interest rate according to a Taylor rule with coefficients \((\gamma_{\pi}, \gamma_x) = (1.5, 0.5)\). We observe that \((i)\) for a given \(\lambda_2\), the larger the weight to the interest rate announcement (lower \(\lambda_1\)), the slower the convergence;\(^{21}\)

\(^{21}\)By allowing for a \(\lambda_1 \neq \lambda_2\) we are able to analyze the case in which different typology of agents in the economy pay different attention to the announcements. For example market operators may pay more attention to interest rate announcements, while workers to inflation expectations. We are also able to study the case in which the communication strategy of the central bank focuses more on a particular macroeconomic variable, depending on the specific macroeconomic environment in which it operates.
Figure 4: E-stability and root-t convergence under no announcement and under announcement only of expected inflation and output gap

Note: Here we are assuming that central bank’s announcement about inflation and output gap expectations, is partially internalized by private agents \((1 - \lambda_2 = 0.25)\)

moreover, \((ii)\) it is sufficient a low weight to the announcement of inflation and output gap in order to increase significantly the speed of convergence; finally \((iii)\) for sufficiently low \(\lambda_1\) and high \(\lambda_2\) the negative effects of the interest rate path dominate the positive effects of the inflation and output announcement. Proposition 6 states formally this last result.\(^{22}\)

\(^{22}\)In any case also when the positive effect of the inflation and output gap announcement dominates, the publication of the interest rate path worsen the properties of the equilibrium in terms of stability and speed of convergence with respect to the case in which the central bank is silent about its own interest rate projections obtained under the erroneous assumption that private agents are perfectly rational.
Table 2: Speed of convergence and simulations

<table>
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<tr>
<th>$\lambda_1$</th>
<th>$\delta$</th>
<th>$\lambda_2 = 0.5$</th>
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<td>0.14</td>
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NOTE: Initial expectation error is 10 per cent of the REE. In all simulations we compute the rate of convergence, $\delta$, with 1000 independent realizations for t=9000 and tz=10000 periods; $T_{1/3}$ indicates number of quarters needed in order to reduce the inflation forecast error to one third of the initial bias. Interest rate rule coefficients are $(\gamma_\pi, \gamma_x) = (1.5, 0.5)$.

Proposition 6. In an economy that (i) evolves according to the system of equation (4.1), where (ii) the central bank publishes both the interest rate path and the inflation and output gap projections consistent with the REE and (iii) private agents give weight $0 < (1 - \lambda_1) \leq 1$ to the former and $0 < (1 - \lambda_2) \leq 1$ to the latter, in order to have condition for E-stability less stringent under no announcement than under announcement, the necessary condition is that

$$0 \leq \lambda_1 < 2 - \frac{(1 - \lambda_2)(1 - \beta^2 \lambda_2)}{\lambda_2 \alpha \varphi (1 + \beta \lambda_2)} - \frac{1}{\lambda_2} \quad (4.3)$$

Proof. See appendix 8. \qed

In Figure 5, region A shows the combination of weights to the two projections
under which the announcement of the paths reduces the region of stability under learning. In particular when private agents give relatively high weights to the interest rate path and low weights to the inflation and output gap projections, transparency increases the region of instability under learning.

Figure 5: Weights to the projections and E-stability when the central bank announces interest rate, inflation and output gap paths

5 Extensions

In this section we focus on some extensions of the baseline model. In particular we analyze how our main results are affected by: (i) the announcement of a longer interest rate path, (ii) a policy rule that responds to expected inflation and output gap and (iii) the announcement also includes a subjective judgmental component.

5.1 Publication of a longer path

One interesting extension considers the case where the central bank announces a longer path. The following proposition states that the longer the horizon $T$ of the announced path, the larger the region of instability.
Proposition 7. In an economy that (i) evolves according to equations (3.8), where (ii) private agents assign weight \(0 \leq (1 - \lambda_1) \leq 1\) to the central bank’s announcement, the longer is the path revealed the more stringent are conditions for E-stability. In particular, the necessary and sufficient condition for the MSV solution to be E-stable when the central bank announces the \(T\)-period path is

\[
\gamma_\pi > \frac{T}{(1 + \lambda_1 (T - 1))} - \frac{(1 - \beta)}{\alpha} \gamma_x
\]  

(5.2)

Proof. See Appendix 9.

Figure 6: E-stability and the announcement of a \(T\)-period interest rate path

Figure 7 reports for different \(Ts\) the regions where the REE is E-stable and shows that for \(T\) sufficiently large, no realistic policy will be able to drive the economy back to the REE.

5.2 Forward expectations in the policy rule

We consider now an expectation-based policy rule:

\[
i_t = \gamma + \gamma_x E_t^* x_{t+1} + \gamma_\pi E_t^* \pi_{t+1}
\]  

(5.3)
so that \( i_t \) is set by the monetary authority in response to forecast of next period inflation and output gap.

As shown in Bullard and Mitra necessary and sufficient conditions for the REE to be E-stable is

\[
\gamma_\pi > 1 - \frac{1 - \beta}{\alpha} \gamma_x
\]  

(5.6)

Proposition 8 shows that under expectation-based policy rules conditions for E-stability when the central bank announces the interest rate path are the same of those obtained under contemporaneous policy rules. In particular, also under the hypothesis that the central bank follows an expectations-based policy rule, revealing the path makes conditions for E-stability more stringent than under no announcement.

**Proposition 8.** Let \( \varphi \gamma_x + \alpha \varphi_\pi + 1 \neq 0 \). In an economy where (i) the central bank follows an expectations-based policy rule (5.3), (ii) at time \( t \) the central bank publishes the time \( t+1 \) interest rate projection consistent with the REE and (iii) private agents give weight \( 0 \leq (1 - \lambda_1) \leq 1 \) to these projections, revealing the path makes condition for E-stability more stringent than under no announcement. In particular, the necessary and sufficient condition for stability under learning (E-stability) of the equilibrium (2.6) is

\[
\gamma_\pi > \frac{2}{(1 + \lambda_1)} - \frac{1 - \beta}{\alpha} \gamma_x.
\]  

(5.7)

**Proof.** See appendix 10. \( \square \)

### 5.3 Announced path with a subjective judgmental component

In the previous sections we have assumed that central banks projections are model consistent and derived under the assumption of rational expectations. Here we investigate the effect of introducing a subjective and judgemental component in the projection. We model this component by introducing a shock in the policy path,\(^{23}\)

\[
E_t^{CB} i_{t+1} = a_i + \rho_u b_u i u_t + \rho_g b_g i g_t + z_t
\]  

(5.8)

\(^{23}\)This is only one way to introduce the judgmental component. A more general analysis is left for future research.
with
\[ z_t = \rho_z z_{t-1} + \varepsilon_{zt} \]  
(5.9)

where \( \varepsilon_{zt} \) is white noises with variances \( \sigma^2_z \). Under this assumption the only elements that change in the system of equations describing the evolution of the economy
\[ y_t = \bar{Q} + \bar{F} \times E_t^* y_{t+1} + \bar{V} \times E_t^* y_{t+2} + \bar{S} w_t, \]  
(5.10)

are the matrix \( \bar{S} \) and the vector of exogenous state variables \( w_t \), that now includes also the \( z_t \) variable.

\[ w'_t = \begin{bmatrix} u_t & g_t & z_t \end{bmatrix}. \]

As the matrices \( \bar{F} \) and \( \bar{V} \) are not affected by the introduction of the additional term in the announced path, all the results in terms of E-stability and speed of convergence obtained in the previous sections hold also when we introduce a judgmental component modeled as an exogenous shock in the projections.

6 Conclusions

In this paper we have studied a standard New-Keynesian economy where private agents are learning, the central bank implements monetary policy through an interest rate rule and it publishes its macroeconomic projections. To stay close to the current practice of most of the central banks which follow this communication strategy we have assumed that projections are obtained under the assumption that the economy is populated by perfectly rational agents.

Our analysis has focused on the effects of such a publication on the stability of the equilibrium and on the speed of convergence of private expectations towards rationality. The main result is that the effect depends on the economic variable which is published. In particular when the central bank reveals information about its own expected interest path, conditions for stability under learning become more stringent and the speed of convergence slows down. In such a situation macroeconomic stability and a faster process of convergence of expectations toward rationality can be restored only if the central bank selects an interest rule that responds more aggressively against inflation. On the contrary, the announcement of expected inflation and output gap enlarges the set of policy rules which are consistent with stability and a fast process of convergence.

Our analysis suggests that a central bank, before deciding to publish interest rate
projections, should investigate the expectation formation process of private agents and assess how far such a mechanism is from perfect rationality. The greater the distance, the higher the risk that the release of interest rate projections might exert adverse effects on the economy. Our analysis suggests that particular attention should be paid to those situations in which private agents, in forming their expectations, are likely to put a larger weight on the announcement of the interest rate path than on the inflation and output gap projections. In those cases, in fact, the set of policy rules that guarantees stability and a fast convergence of expectations could be even smaller than in the no announcement case.

It is finally worthwhile to notice that our analysis is not necessarily against the publication of interest rate projections when agents are learning. If on one side we have concluded that in this case the publication of rational interest rate projection exerts a negative effect on the economy, on the other the central bank by providing to the public alternative interest rate projections that take into account the true expectation formation process of private agents, could strengthen the macroeconomic stability and increase the speed of convergence of private expectations towards perfect rationality.
References


Appendix: Proofs of propositions

Appendix 1) The REE under contemporaneous Taylor rules

Under the set of policies

\[ i_t = \gamma + \gamma_x x_t + \gamma_\pi \pi_t \]

the economy evolves according to the following stochastic dynamic system:

\[ H y_t = K + L \times E_t^* y_{t+1} + M w_t, \]

with

\[
\begin{align*}
y_t &= \begin{bmatrix} \pi_t \\ x_t \\ i_t \end{bmatrix}, \\
w_t &= \begin{bmatrix} u_t \\ g_t \end{bmatrix}, \\
\Psi &= \begin{bmatrix} \rho_u & 0 \\ 0 & \rho_g \end{bmatrix}, \\
\varepsilon_t &\sim N(0, \Omega_\varepsilon)
\end{align*}
\]

\[
H = \begin{bmatrix} 1 & -\alpha & 0 \\ 0 & 1 & \varphi \\ -\gamma_\pi & -\gamma_x & 1 \end{bmatrix}, \\
K = \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \\
L = \begin{bmatrix} \beta & 0 & 0 \\ \varphi & 1 & 0 \end{bmatrix}, \\
M = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}
\]

To calculate the minimum state variable (MSV) solution, we rewrite the system as

\[ y_t = Q + F \times E_t^* y_{t+1} + S w_t, \]

where

\[ F = H^{-1} L, \quad Q = H^{-1} K, \quad S = H^{-1} M \]

The MSV solution satisfies

\[
\begin{align*}
A &= Q + FA \\
B &= FB\Psi + S
\end{align*}
\]

and, therefore,

\[
A = (I - F)^{-1} Q \\
\text{vec}(B) = (I - \Psi' \otimes F)^{-1} \text{vec}(S).
\]
For determinacy we need all the eigenvalues of the $F$ matrix to be inside the unit circle (Bullard and Mitra, 2001). One of the eigenvalues is equal to 0 and the other two can be obtained as a solution of the characteristic polynomial

$$X^2 + a_1X + a_2.$$ 

The necessary and sufficient condition for determinacy is $|a_2| < 1$ and $|a_1| < 1 + a_2$. This reduces to have

$$\gamma_\pi > 1 - \frac{(1 - \beta)}{\alpha} \gamma_x.$$ 

For E-stability we need the eigenvalues of the $F - I$ matrix and those of the $\left(\frac{dF\Psi dB}{dB} - I\right)$ matrix to have the real part smaller than zero.

Since one of the eigenvalues of the $F - I$ matrix is equal to −1 and the others can be obtained from the characteristic polynomial

$$X^2 + a_1X + a_2,$$

where

$$a_1 = a_2 + c, \text{ with } c > 0$$

the necessary and sufficient condition for E-stability, $a_2 > 0$ and $a_1 > 0$, reduces to have $a_2 > 0$, that is

$$\gamma_\pi > 1 - \frac{(1 - \beta)}{\alpha} \gamma_x.$$ 

It is easy to show that as $\rho_u$ and $\rho_g$ are smaller than 1 the previous condition is also sufficient for the eigenvalues of the $\left(\frac{dF\Psi dB}{dB} - I\right)$ matrix to have the real part smaller than zero.

**Appendix 2) Proof of proposition 1 (Announcement of the policy path and E-stability of the REE)**

To study how the economy evolves under learning we rewrite the system as

$$\tilde{H}y_t = \tilde{K} + \tilde{L} \times E_t^* y_{t+1} + \tilde{P} \times E_t^* y_{t+2} + \tilde{M} w_t,$$
where

\[
y_t = \begin{bmatrix} \pi_t \\ x_t \\ i_t \end{bmatrix}, \quad \tilde{K} = \begin{bmatrix} 0 & -\varphi (1 - \lambda) a_i \\ -\gamma \end{bmatrix}, \quad \tilde{P} = \begin{bmatrix} \beta^2 & 0 & 0 \\ \varphi & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}
\]

\[
\tilde{H} = \begin{bmatrix} 1 & -\alpha & 0 \\ 0 & 1 & \varphi \\ -\gamma \pi & -\gamma \varphi & 1 \end{bmatrix}, \quad \tilde{L} = \begin{bmatrix} 0 & \beta \alpha & 0 \\ \varphi & 0 & -\varphi \lambda_1 \\ 0 & 0 & 0 \end{bmatrix},
\]

\[
\tilde{M} = \begin{bmatrix} 1 + \beta \rho_u & 0 \\ -\varphi (1 - \lambda_1) \rho_u b_{u,i} & 1 + (1 - \varphi (1 - \lambda_1) b_{g,i}) \rho_g \\ 0 & 0 \end{bmatrix}
\]

or

\[
y_t = \tilde{Q} + \tilde{F} \times E_t^s Y_{t+1} + \tilde{V} \times E_t^s Y_{t+2} + \tilde{S} w_t,
\]

where

\[
\tilde{F} = \tilde{H}^{-1} \tilde{L} \quad \text{and} \quad \tilde{V} = \tilde{H}^{-1} \tilde{P}.
\]

For E-stability we need the eigenvalues of the \( \tilde{F} + \tilde{V} - I \) matrix and of the \( \left( \frac{d(FB\Psi + V B\Psi^\prime \Psi)}{dB} - I \right) \) matrix to have the real part smaller than zero.

The characteristic polynomial of the \( \tilde{F} + \tilde{V} - I \) matrix is

\[
(X + 1) \left( X^2 + a_1 X + a_2 \right)
\]

and the necessary and sufficient conditions for E-stability are \( a_2 > 0 \) and \( a_1 > 0 \). As

\[
a_1 = a_2 + c, \quad \text{with} \quad c > 0
\]

the necessary and sufficient condition for E-stability is just \( a_2 > 0 \), that is

\[
\gamma \pi > \frac{2}{(1 + \lambda_1)} - \frac{(1 - \beta)}{\alpha} \gamma \varphi
\]

We also need the eigenvalues of the \( \left( \frac{d(FB\Psi + V B\Psi^\prime \Psi)}{dB} - I \right) \) matrix to be smaller than zero.

Proceeding as we have done for the matrix \( \tilde{F} + \tilde{V} - I \), it is easy to show that whenever the previous condition is satisfied also the eigenvalues of \( \left( \frac{d(FB\Psi + V B\Psi^\prime \Psi)}{dB} - I \right) \) have real part smaller than zero.
Appendix 3) proof of proposition 2 (Announcement of policy intentions and root-t convergence)

From Marcet and Sargent (1992) it follows that a necessary condition for root-t convergence is that the eigenvalues of $\tilde{F} + \tilde{V}$ and those of $\frac{d(FB\Psi + \tilde{V}B\Psi')}{dB}$ have the real part smaller than $\frac{1}{2}$. On the other hand, agents beliefs will not converge to the MSV solution at root-t speed if any eigenvalue of $\tilde{F} + \tilde{V}$ or $\frac{d(FB\Psi + \tilde{V}B\Psi')}{dB}$ has real part more than $\frac{1}{2}$. Similarly to the proof in Appendix 2, it turns out that it is sufficient to have the real part of the eigenvalues of $\tilde{F} + \tilde{V}$ smaller than $\frac{1}{2}$.

The characteristic polynomial of $\tilde{F} + \tilde{V} - \frac{1}{2}I$ is

$$(X + 1)\left(X^2 + a_1 X + a_2\right)$$

By applying the Routh theorem, the necessary and sufficient condition for root-t convergence that both eigenvalues of $\tilde{F} + \tilde{V}$ have real parts less than $\frac{1}{2}$ (i.e. both eigenvalues of $\tilde{F} + \tilde{V} - \frac{1}{2}I$ have negative real parts) reduces to have $a_1 > 0$ and $a_2 > 0$. Under the assumption that $\gamma_x$ and $\gamma_\pi$ are non negative, the necessary and sufficient condition is:

$$\gamma_\pi > \max\left[\frac{(\beta^2 + 2\alpha \varphi)}{\alpha \varphi (1 + \lambda_1 + \beta)} - \frac{(1 + \lambda_1 - \beta^2)}{\alpha (1 + \lambda_1 + \beta)} \gamma_x}{\frac{4(2\beta + 1)\alpha \varphi - (2\beta^2 - 1)}{(2\beta + 1)(1 + 2\lambda_1)\alpha \varphi} + \frac{2(\beta^2 - 1)}{(1 + 2\beta)\alpha} \gamma_x}\right]$$

Appendix 4) proof of proposition 3 (Root-t convergence under different weights to policy path announcement)

Given the set

$$S_1 = \left\{\gamma_\pi, \gamma_x : \gamma_\pi > \max\left[\frac{(\beta^2 + 2\alpha \varphi)}{\alpha \varphi (1 + \lambda_1 + \beta)} - \frac{(1 + \lambda_1 - \beta^2)}{\alpha (1 + \lambda_1 + \beta)} \gamma_x}{\frac{4(2\beta + 1)\alpha \varphi - (2\beta^2 - 1)}{(2\beta + 1)(1 + 2\lambda_1)\alpha \varphi} - \frac{(1 - 2\beta^2)}{(1 + 2\beta)\alpha} \gamma_x}\right]\right\}$$

under which we have root-t convergence, we take derivatives of the two terms inside the max operator with respect to $\lambda_1$ and we show that the larger the $\lambda_1$, that is the smaller the weight to the announcement (the extreme cases of $\lambda_1 = 1$ coincide with the case of no announcement), the smaller is the $S_1$ set, since the larger has to be $\gamma_\pi$ in order to stay in the $S_1$ set.
As
\[
\frac{\partial (1 + \lambda_1 - \beta^2)}{\alpha (1 + \lambda_1 + \beta)} > 0
\]
and
\[
\frac{\partial (\beta^2 + 2\alpha\varphi)}{(1 + \beta + \lambda_1)\alpha\varphi} < 0,
\]
the first term of the max function is larger for smaller \(\lambda_1\).

And since
\[
\frac{\partial 4(2\beta + 1)\alpha\varphi - (2\beta^2 - 1)}{(2\beta + 1)(1 + 2\lambda_1)\alpha\varphi} < 0
\]
for
\[\alpha\varphi > 0.08,\]
condition that is always satisfied for all reasonable values of \(\alpha\varphi\) (for example under CGG (1999) parametrization \(\alpha\varphi = 0.3\); under Woodford (2003) parametrization \(\alpha\varphi = 0.15\)), the second term of the max function is larger for smaller \(\lambda_1\).

Therefore, the larger \(\lambda_1\), the smaller the set of \((\gamma_\pi, \gamma_x)\) combinations under which we have root-T convergence.

**Appendix 5) Speed of convergence isoquants**

We look at combinations of \((\gamma_\pi, \gamma_x)\) that results in the same value for the real part of the largest eigenvalue of the \(\tilde{F} + \tilde{V}\) matrix. Let \(0 < k < 1\), then
\[z^2 + a_k^1 z + a_k^2\]
is the characteristic polynomial of \(\tilde{F} + \tilde{V} - kI\).

Both eigenvalues of \(\tilde{F} + \tilde{V}\) have real parts less than \(k\) (i.e. both eigenvalues of \(\tilde{F} + \tilde{V} - kI\) have negative real parts) if and only if \(a_k^1 > 0\) and \(a_k^2 > 0\), that is,
\[\gamma_\pi = \max \left[ \frac{(1 - 2k + \beta^2 + 2\alpha\varphi)}{(2k + \beta + \lambda_1)\alpha\varphi} - \frac{(-\beta^2 + 2k + \lambda_1)\alpha\varphi}{2\alpha\varphi(k + \beta) - (\beta^2 - k)(1 - k)} \right].\]

**Appendix 6) proof of proposition 4 (Speed of convergence and communication of the path)**
Let’s consider an isoquant in the $S_2$ set:

$$
\gamma^k_{x\pi} = \max \left[ \frac{\left(1-2k+\beta^2+2\alpha\varphi\right)}{(2k+\beta+\lambda_1)\alpha\varphi} \gamma^k_x - \left(\frac{-\beta^2+2k+\lambda_1}{(2k+\beta+\lambda_1)\alpha}\right)\gamma^x_x \right] \quad \text{for } \frac{1}{2} \leq k \leq 1
$$

We take derivatives of the two terms inside the max operator with respect to $\lambda_1$ and we show that for a given $k$, the larger the $\lambda_1$, that is the smaller the weight to the announcement (the extreme cases of $\lambda_1 = 1$ coincide with the case of no announcement), the smaller is $\gamma^k_{x\pi}$.

As

$$
\frac{\partial \left(-\beta^2+2k+\lambda_1\right)}{(2k+\beta+\lambda_1)\alpha} > 0
$$

and

$$
\frac{\partial \left(1-2k+\beta^2+2\alpha\varphi\right)}{(2k+\beta+\lambda_1)\alpha\varphi} < 0
$$

for

$$
k < \frac{1+\beta^2}{2} + \alpha\varphi
$$

and since

$$
\frac{1+\beta^2}{2} + \alpha\varphi > 1
$$

for all reasonable values of $\alpha, \varphi, \beta$, it is $\frac{\partial \left(1-2k+\beta^2+2\alpha\varphi\right)}{(2k+\beta+\lambda_1)\alpha\varphi} < 0$. Therefore, first term of the max function is larger for smaller $\lambda_1$.

Moreover, for $\frac{1}{2} \leq k \leq 1$,

$$
\frac{\partial \left(2\alpha\varphi(k+\beta)-(\beta^2-k)(1-k)\right)}{\alpha\varphi(k+\beta)(k+\lambda_1)} < 0
$$

for

$$
\alpha\varphi > 0.08,
$$

condition that we have already seen is always satisfied for all reasonable values of $\alpha\varphi$. Therefore, also the second term of the max function is larger for smaller $\lambda_1$.

Therefore for a given $\gamma^k_x$, the larger is $\lambda_1$, the smaller has to be $\gamma^k_{x\pi}$ in order to reach the same speed of convergence denoted by the k-isoquant. Or in other terms, for a given combination of $\gamma^k_x, \gamma^k_{x\pi}$, the larger is $\lambda_1$ the smaller is $k$, and the fastest the learning process.
Appendix 7) proof of proposition 5 (Announcing expected inflation and output gap)

Under learning the economy evolves according to the system of equation

\[
\tilde{H} y_t = \tilde{K} + \tilde{L} \times E_t^* y_{t+1} + \tilde{P} \times E_t^* y_{t+2} + \tilde{M} w_t,
\]

and the \(\tilde{H}, \tilde{L}\) and \(\tilde{P}\) matrices that are relevant in order to study stability under learning are

\[
\begin{bmatrix}
1 & -\alpha & 0 \\
0 & 1 & \varphi \\
-\gamma_\pi & -\gamma_x & 1
\end{bmatrix},
\begin{bmatrix}
\lambda_2 \beta^2 & 0 & 0 \\
\varphi \lambda_2 & \lambda_2 & 0 \\
0 & 0 & 0
\end{bmatrix}
\]

or

\[
y_t = \tilde{Q} + \tilde{F} \times E_t^* y_{t+1} + \tilde{V} \times E_t^* y_{t+2} + \tilde{S} w_t,
\]

where

\[
\tilde{F} = \tilde{H}^{-1} \tilde{L}, \quad \tilde{V} = \tilde{H}^{-1} \tilde{P}.
\]

Necessary and sufficient condition for E-stability is that the eigenvalues of the \(\tilde{F} + \tilde{V} - I\) matrix have the real part smaller than zero.

The characteristic polynomial of this matrix is

\[
(X + 1) \left( X^2 + a_1 X + a_2 \right).
\]

All eigenvalues of \(\tilde{F} + \tilde{V} - I\) have real parts smaller than zero if and only if \(a_1 > 0\) and \(a_2 > 0\), but since

\[
a_1 = a_2 + c
\]

with \(c > 0\), the necessary and sufficient condition for E-stability is just \(a_2 > 0\), that is

\[
\gamma_\pi > \frac{2 \lambda_2}{(1 + \lambda_1)} - \frac{(1 - \beta^2 \lambda_2)(1 - \lambda_2)}{\alpha \varphi (1 + \beta \lambda_2)(1 + \lambda_1)} - \frac{(1 - \beta^2 \lambda_2)}{\alpha (1 + \beta \lambda_2)} \gamma_x
\]

In order to determine the effect of announcing only the expected inflation and
expected output gap, we impose \( \lambda_1 = 1 \) and obtain the following condition:

\[
\gamma_\pi > h - z \gamma_x
\]

with

\[
h = \lambda_2 - \frac{(1 - \beta^2 \lambda_2) (1 - \lambda_2)}{2 \alpha \varphi (1 + \beta \lambda_2)}
\]

\[
z = \frac{(1 - \beta^2 \lambda_2)}{\alpha (1 + \beta \lambda_2)}.
\]

Since

\[
\frac{\partial h}{\partial \lambda_2} > 0 \quad \text{and} \quad \frac{\partial z}{\partial \lambda_2} < 0,
\]

we have that the larger the weight to the projection (the lower \( \lambda_2 \)), the lower the intercept \( h \) and the steeper the slope (in absolute value) \( z \).

Therefore, for all values of the parameters, we have that by announcing the expected inflation and output gap, the combinations of \((\gamma_x, \gamma_\pi)\) that imply E-instability is a subset of those obtained when the central bank does not announce the inflation and output gap.

In order to study the speed of convergence, we consider the \( k \)-isoquant obtained from the \( \tilde{F} + \tilde{V} - k I \) matrix. We look at combinations of \((\gamma_\pi, \gamma_x)\) that result in the same value for the real part of the largest eigenvalue of the \( \tilde{F} + \tilde{V} \) matrix. Let \( 0 < k < 1 \), then

\[
(z + k) \left( z^2 + a_1^k z + a_2^k \right)
\]

is the characteristic polynomial of \( \left( \tilde{F} + \tilde{V} - k I \right) \). Both eigenvalues of \( \tilde{F} + \tilde{V} \) have real parts less than \( k \) (i.e. both eigenvalues of \( \tilde{F} + \tilde{V} - k I \) have negative real parts) if and only if \( a_1^k > 0 \) and \( a_2^k > 0 \), that is

\[
\gamma_\pi > \frac{(1 + \beta^2 + 2 \alpha \varphi) \lambda_2 - 2k}{\alpha \varphi (2k + \lambda_1 + \beta \lambda_2)} - \frac{2k + \lambda_1 - \beta^2 \lambda_2}{\alpha (2k + \lambda_1 + \beta \lambda_2)} \gamma_x
\]

and

\[
\gamma_\pi > \frac{2 \lambda_2}{(\lambda_1 + k)} - \frac{(\lambda_2 - k) (\beta^2 \lambda_2 - k)}{\alpha \varphi (\beta \lambda_2 + k) (\lambda_1 + k)} - \frac{(k - \beta^2 \lambda_2)}{\alpha (\beta \lambda_2 + k) \gamma_x}.
\]
A k-isoquant in the $S_2$ set satisfies:

\[ \gamma_k^\pi = \max \left[ \frac{(1+\beta^2+2\alpha\varphi)\lambda_2-2k}{\alpha\varphi(2k+\lambda_1+\beta\lambda_2)} - \frac{2k+\lambda_1-\beta^2\lambda_2}{\alpha(2k+\lambda_1+\beta\lambda_2)} \gamma_x, \frac{(\lambda_2-k)(\beta^2\lambda_2-k)}{\alpha\varphi(\lambda_2+1)(\lambda_1+k)} - \frac{(k-\beta^2\lambda_2)}{\alpha(\lambda_2+1)} \gamma_x \right] \text{ for } \frac{1}{2} \leq k \leq 1
\]

Following the steps suggested in the proof of proposition 4, we obtain that the larger the $\lambda_2$, the larger is $\gamma_k^\pi$.

**Appendix 8) proof of proposition 6 (Publishing interest rate, inflation and output gap projections)**

Condition for E-stability becomes

\[ \gamma_\pi > h - z\gamma_x \]

with

\[ h = \frac{2\lambda_2}{(1+\lambda_1)} - \frac{(1-\beta^2\lambda_2)(1-\lambda_2)}{\alpha\varphi(1+\beta\lambda_2)(1+\lambda_1)} \]

\[ z = \frac{(1-\beta^2\lambda_2)}{\alpha(1+\beta\lambda_2)} \gamma_x \]

Here we are interested on the combinations of $\lambda_1$ and $\lambda_2$ that make announcement worse than no announcement.

Under no announcement we have

\[ \gamma_\pi > 1 - \frac{(1-\beta)}{\alpha} \gamma_x. \]

comparing the slope under announcement and under no announcement we have

\[ \frac{(1-\beta^2\lambda_2)}{(\beta\lambda_2 + 1)\alpha} - \frac{(1-\beta)}{\alpha} = \frac{(1-\lambda_2)\beta}{(\beta\lambda_2 + 1)\alpha} \geq 0 \]

for all values of $0 \leq \lambda_2 \leq 1$.

The intercept

\[ 1 - \frac{2\lambda_2}{(1+\lambda_1)} + \frac{(1-\beta^2\lambda_2)(1-\lambda_2)}{\alpha\varphi(1+\beta\lambda_2)(1+\lambda_1)} < 0 \]

for
\[ 0 \leq \lambda_1 < 2 - \frac{(1 - \lambda_2)(1 - \beta^2 \lambda_2)}{\lambda_2 \alpha \varphi (1 + \beta \lambda_2)} - \frac{1}{\lambda_2} \]

where

\[ 2 - \frac{(1 - \lambda_2)(1 - \beta^2 \lambda_2)}{\lambda_2 \alpha \varphi (1 + \beta \lambda_2)} - \frac{1}{\lambda_2} \leq 1 \]

for all values of \( \lambda_2 \leq 1 \), since

\[(1 - \beta^2 \lambda_2)(1 - \lambda_2) + \alpha \varphi (1 - \lambda_2) + (1 - \lambda_2) \alpha \beta \varphi \lambda_2 \geq 0\]

**Appendix 9) Proof of proposition 7 (Announcement of a T-period path)**

We rewrite

\[
\pi_t = \beta^T E_t^* \pi_{t+T} + E_t^P \sum_{j=0}^{T-1} \beta^j (\alpha x_{t+j} + u_{t+j})
\]

\[
x_t = E_t^* x_{t+T} - E_t^P \sum_{j=0}^{T-1} (\varphi i_{t+j} - \varphi \pi_{t+j+1} - g_{t+j})
\]

\[E_t^P y_{t+j} = (1 - \lambda_i) E_t^C y_{t+j} + \lambda_i E_t^* y_{t+j}, \text{ where } i = 1 \text{ for the } i_t \text{ and } i = 2 \text{ for } \pi_t \text{ and } x_t\]

as

\[A_0 Y_t = K + A_1 E_t^* Y_{t+1} + ... + A_{T-1} E_t^* Y_{t+T-1} + A_T E_t^* Y_{t+T} + Sw_t\]

where

\[
A_0 = \begin{bmatrix}
1 & -\alpha & 0 \\
0 & 1 & \varphi \\
-\gamma_{\pi} & -\gamma_x & 1
\end{bmatrix},
\]

\[
A_{T-1} = \begin{bmatrix}
0 & \lambda_2 \alpha \beta^{T-1} & 0 \\
\lambda_2 \varphi & 0 & -\lambda_1 \varphi \\
0 & 0 & 0
\end{bmatrix},
\]

\[
A_T = \begin{bmatrix}
\lambda_2 \beta^T & 0 & 0 \\
\lambda_2 \varphi & \lambda_2 & 0 \\
0 & 0 & 0
\end{bmatrix}.
\]
Since the perceived law of motion (PLM) is

\[ E^*_t Y_{t+T} = A + B \Psi^T w_t \]

we can rewrite the previous expression as

\[ A_0 Y_t = K + A_1 (A + B \Psi w_t) + \ldots + A_{T-1} (A + B \Psi^{T-1} w_t) + A_T (A + B \Psi^T w_t) + S w_t. \]

Therefore, the actual law of motion (ALM) is

\[ Y_t = A_0^{-1} K + A_0^{-1} (A_1 + \ldots + A_T) A + (A_0^{-1} A_1 B \Psi + \ldots + A_0^{-1} A_T B \Psi^T + A_0^{-1} S) w_t, \]

And the mappings from the PLM to the ALM are

\[ T (A) - A = A_0^{-1} (A_1 + \ldots + A_T) A - A \]

\[ T (B) - B = A_0^{-1} (A_1 B \Psi + \ldots + A_T B \Psi^T) - B \]

To study the E-stability conditions we just need to focus on the \( A_0^{-1} (A_1 + \ldots + A_T) \) matrix, where

\[
(A_1 + \ldots + A_T) = \begin{bmatrix}
\beta^T \lambda_2 & \alpha \lambda_2 \Sigma_{\beta} & 0 \\
T \varphi \lambda_2 & \lambda_2 & -(T - 1) \varphi \lambda_1 \\
0 & 0 & 0
\end{bmatrix}
\]

and \( \Sigma_{\beta} = (\beta + \beta^2 + \ldots + \beta^{T-1}) \).

In particular necessary and sufficient condition for E-stability is that all eigenvalues of the \( [A_0^{-1} (A_1 + A_2 + \ldots + A_{T-1} + A_T) - I] \) matrix have the real part smaller than zero.

The characteristic polynomial of the matrix \( [A_0^{-1} (A_1 + A_2 + \ldots + A_{T-1} + A_T) - I] \) is

\[
\frac{(X + 1) (X^2 + a_1 X + a_2)}{(\varphi \gamma x + \alpha \varphi \gamma \pi + 1)^2}
\]

Necessary and sufficient conditions for E-stability are

\[ a_1, a_2 > 0 \]

and since
\[ a_1 = a_2 + c \]

with \( c > 0 \), it is sufficient that \( a_2 > 0 \), that is

\[ \gamma > \frac{T \lambda_2}{(1 + (T - 1) \lambda_1)} - \frac{(1 - \lambda_2)(1 - \beta^T \lambda_2)}{\alpha \varphi (1 + (T - 1) \lambda_1)(1 + \lambda_2 \Sigma \beta)} - \frac{(1 - \beta^T \lambda_2)}{\alpha (1 + \lambda_2 \Sigma \beta)} \gamma_x. \]

In particular, for \( \lambda_2 = 1 \), i.e. no announcement of inflation and output gap, we have

\[ \gamma > \frac{T}{(1 + (T - 1) \lambda_1)} - \frac{(1 - \beta)}{\alpha} \gamma_x. \]

and since the derivative of the intercept with respect to \( T \)

\[ \frac{\partial}{\partial T} \left( \frac{T}{(1 + (T - 1) \lambda_1)} \right) = \frac{1 - \lambda_1}{(1 + (T - 1) \lambda_1)^2} \geq 0 \]

for \( 0 \leq \lambda_1 \leq 1 \), the longer the path announced, the larger the region of E-instability.

**Appendix 10) Proof of proposition 8 (Expectations-based policy rule)**

Under the set of policies

\[ i_t = \gamma + \gamma_x E_t x_{t+1} + \gamma \pi E_t \pi_{t+1} \]

the economy evolves according to the following stochastic dynamic system:

\[ HY_t = K + L \times E_t Y_{t+1} + M w_t, \]

with

\[
\begin{align*}
y_t &= \begin{bmatrix} \pi_t \\ x_t \end{bmatrix}, \quad w_t = \begin{bmatrix} u_t \\ g_t \end{bmatrix}, \quad \Psi = \begin{bmatrix} \rho_u & 0 \\ 0 & \rho_g \end{bmatrix}, \quad M = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \\
H &= \begin{bmatrix} 1 & -\alpha \\ 0 & 1 \end{bmatrix}, \quad K = \begin{bmatrix} 0 \\ -\varphi \gamma \end{bmatrix}, \quad L = \begin{bmatrix} \beta & 0 \\ \varphi (1 - \gamma) & (1 - \varphi \gamma_x) \end{bmatrix}
\end{align*}
\]

or

\[ Y_t = Q + F \times E_t^* Y_{t+1} + S w_t, \]
with

\[ F = H^{-1}L, \quad Q = H^{-1}K, \quad S = H^{-1}M \]

As shown in Bullard and Mitra (2002), necessary and sufficient condition for E-stability is

\[ \gamma_\pi > 1 - \frac{(1 - \beta)}{\alpha} \gamma_x. \]

Under announcement of the policy path we rewrite the system as

\[ Y_t = \tilde{Q} + \tilde{F} \times E_t^*Y_{t+1} + \tilde{V} \times E_t^*Y_{t+2} + \tilde{S}w_t. \]

Necessary and sufficient condition for E-stability is that the eigenvalues of the \( \tilde{F} + \tilde{V} - I \) matrix have real part smaller than zero.

Since the characteristic polynomial of \( \tilde{F} + \tilde{V} - I \) is

\[ X^2 + a_1 X + a_2 \]

the necessary and sufficient condition for the eigenvalues of the \( \tilde{F} + \tilde{V} \) matrix to have real part smaller than one is \( a_1, a_2 > 0 \). As \( a_1 = a_2 + c \), where \( c > 0 \), the necessary and sufficient condition for the eigenvalues of the \( \tilde{F} + \tilde{V} \) matrix to have real part smaller than one is just \( a_2 > 0 \), that is

\[ \gamma_\pi > \frac{2}{(1 + \lambda_1)} - \frac{(1 - \beta)}{\alpha} \gamma_x. \]